

ISTOSMJERNI STROJEVI

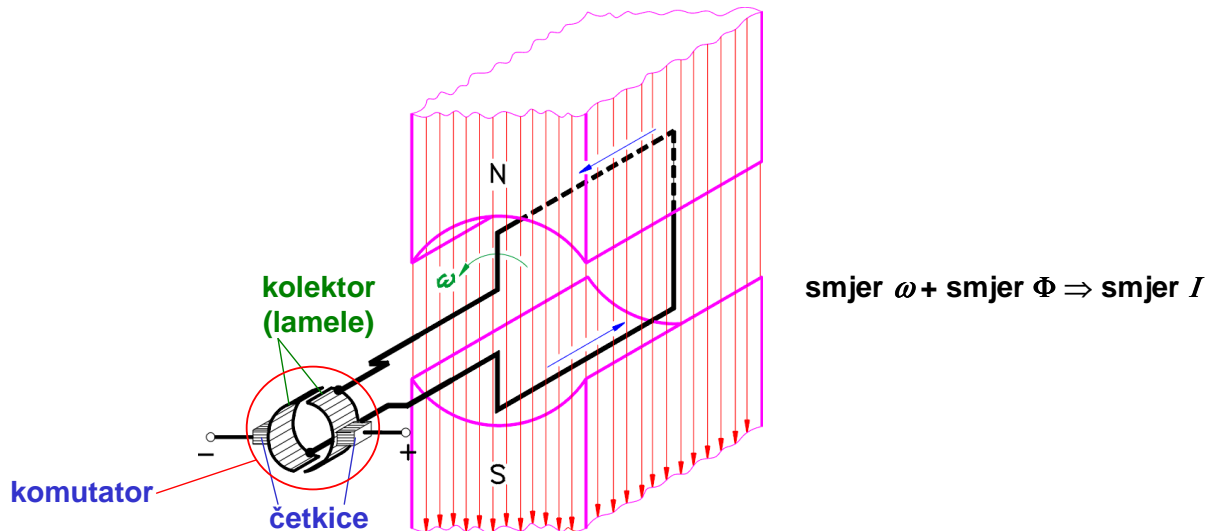
jedini strojevi do Tesle a onda marginalizirani

bili nezamjenjivi za promjenjivu brzinu vrtnje i promjenjivi moment
glavna mana komutacija (održavanje i smetnje)

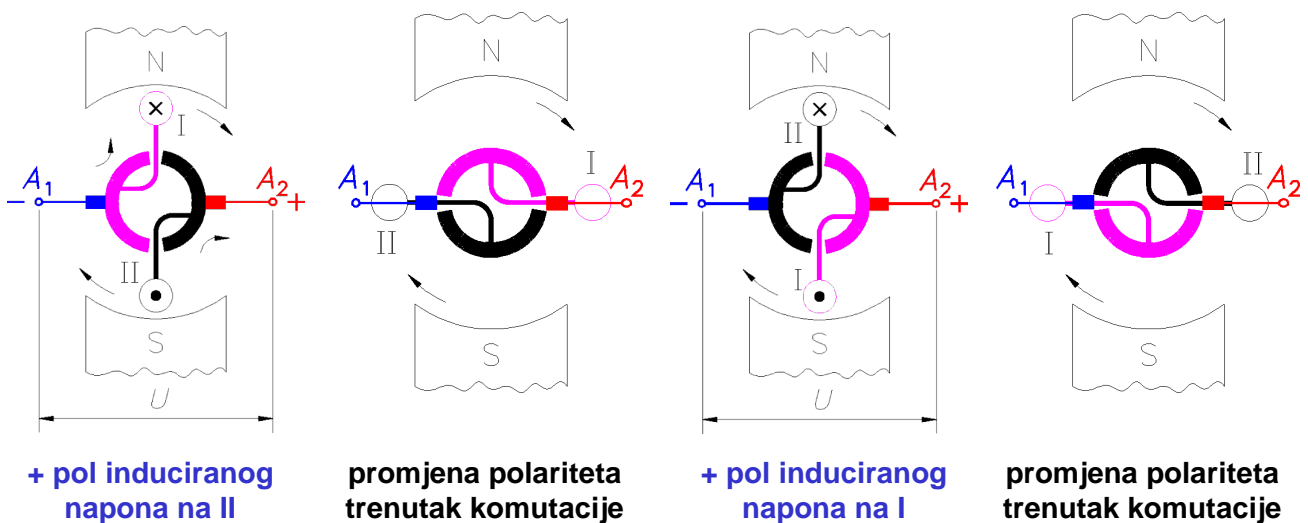
danas - nezavisna uzbuda s poluvodičkim komponentama i komutacijom na statoru

uzbudni namot na statoru - armaturni namot na rotoru

Induciranje istosmjernog napona



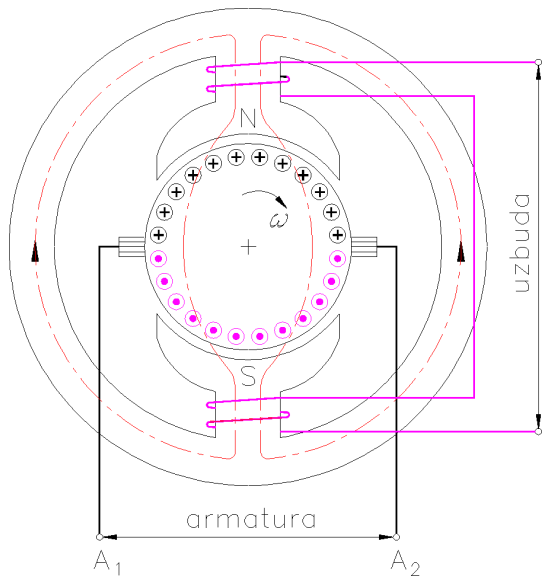
Komutiranje induciranog napona (struje) u istosmjerni



četkice u neutralnoj zoni (okomito na glavno magnetno polje)

komutacija pri trenutna vrijednosti induciranog napona 0

dvopolni stroj

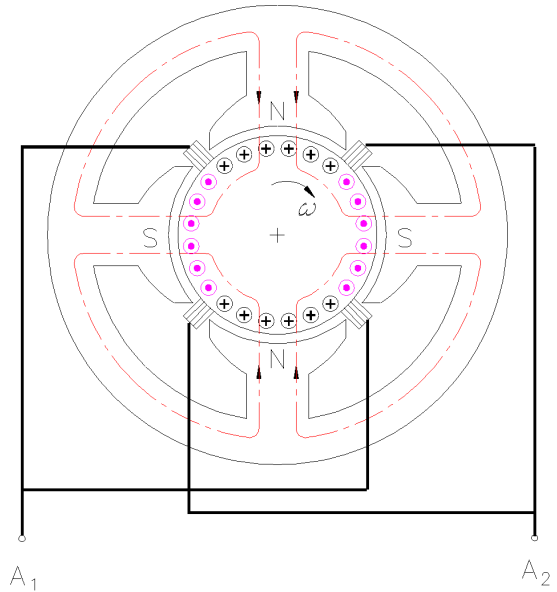


jedno

homogenih magnetnih polja

cijeli ciklus = jedan okretaj

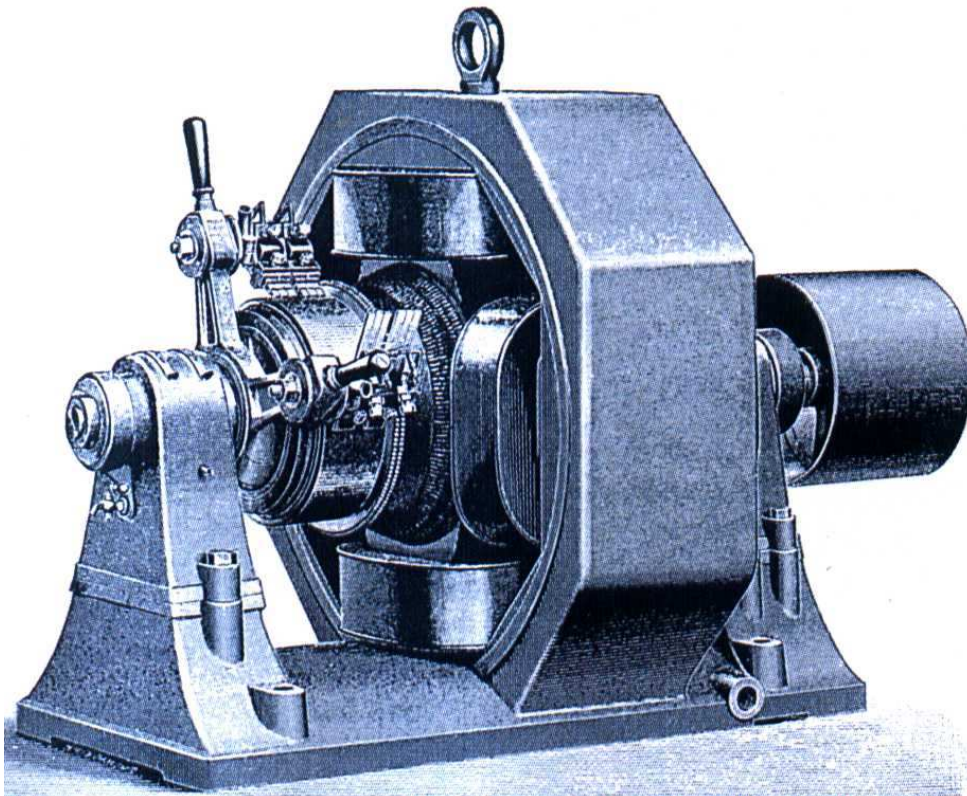
četveropolni stroj



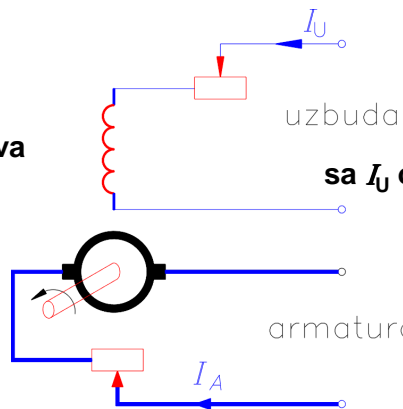
dva

cijeli ciklus = pola okretaja

uz jednak n namota rotora za jednake vrijednosti napona \Rightarrow više polova = manja brzina vrtnje



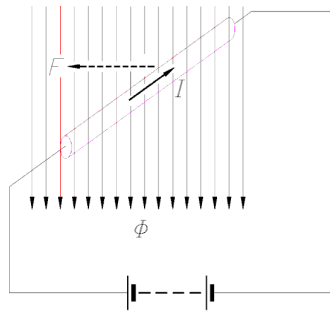
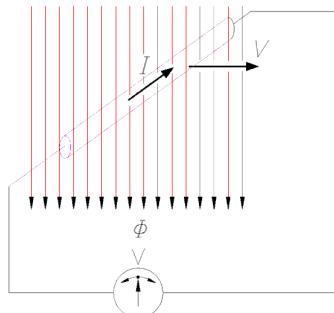
strujni krugovi
istosmjernih strojeva



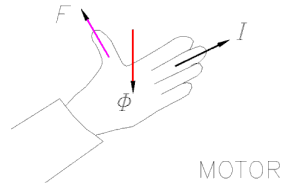
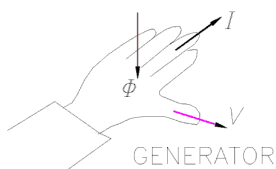
nezavisni (regulirani pogoni)
zavisni (stalni odnos I_U i I_A)

sa I_U određivanje $B \Rightarrow$ inducirani U armature

sa I_A biranje funkcije stroja



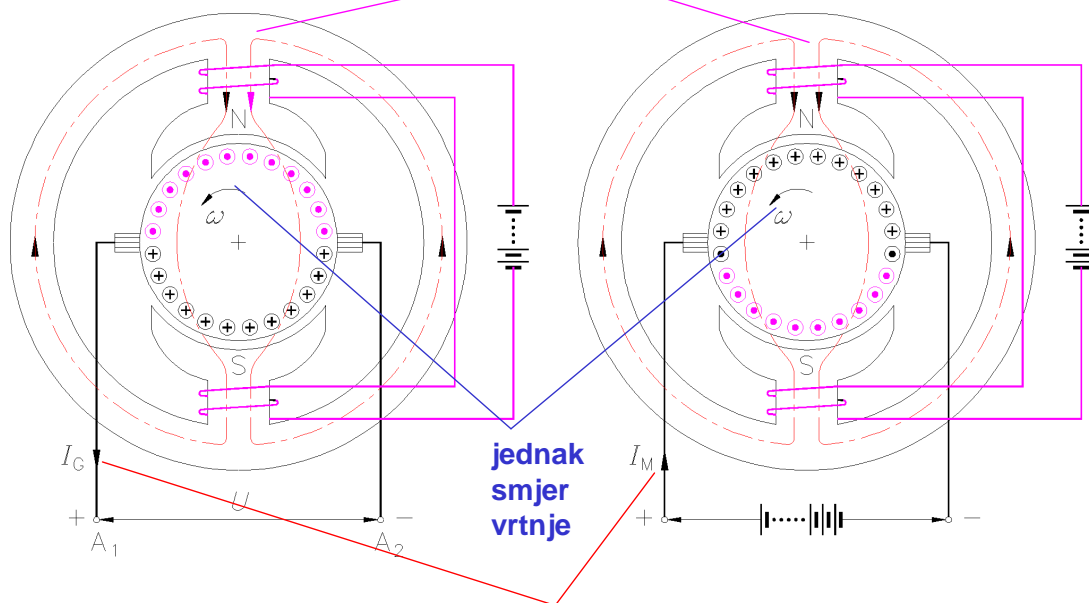
za isti smjer struje i
magnetnog polja
suprotni smjerovi
gibanja vodiča kod
generatora imotora



istosmjerni generator

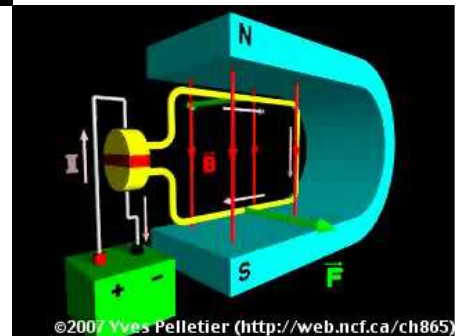
istosmjerni motor

jednak smjer struje uzbuđe (magnetskog polja uzbuđe)

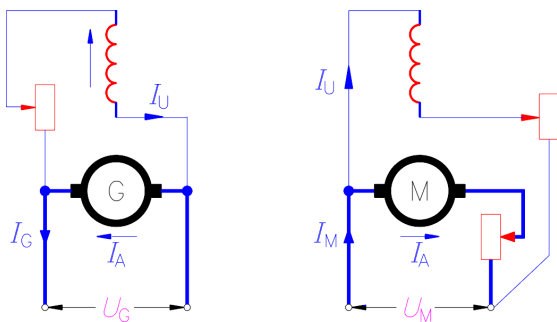


jednak
smjer
vrtnje

suprotni smjerovi struja armatura



zavisni (paralelni) istosmjerni strojevi



srednja vrijednost induciranog napona rotora

$$u_{is} = N \frac{\Delta\Phi}{\Delta t} \quad \text{uz } \Delta\Phi = 2 \cdot \Phi \quad \text{i} \quad \Delta t = \frac{60}{n \cdot p}$$

zavoji rotora +Φ do -Φ vrtnja polova

a ukupni inducirani napon

$$E = 2 \cdot \Phi \cdot \frac{N}{z} \cdot \frac{n \cdot p}{60} = \frac{\Phi \cdot N \cdot n \cdot p}{30 \cdot z} \quad (\text{V})$$

paralelnih grana namota

ili $E = B \cdot l \cdot v \quad (\text{V})$

pad napona na namotu rotora (armature)

$$\Delta U_A = I_A \cdot R_A$$

uz poznati E za generator $U = E - I_A \cdot R_A$
 U (stezaljke) za motor $U = E + I_A \cdot R_A$

prema \Rightarrow

$$E = k \cdot \Phi \cdot n \quad \uparrow \Phi \Rightarrow \uparrow E (U)$$

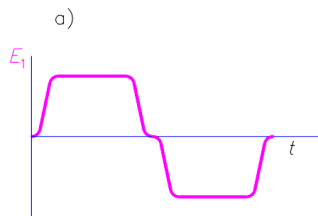
$$n = \frac{E}{k \cdot \Phi} \approx \frac{U}{k \cdot \Phi} \quad \uparrow \Phi \Rightarrow \downarrow n \quad \text{i} \Leftrightarrow$$

sila je $F = B \cdot I \cdot l \quad (\text{N})$ a moment motora $M = 2 \cdot F \cdot r = B \cdot I \cdot l \cdot 2r = B \cdot S \cdot I = \Phi \cdot I \quad (\text{Nm})$

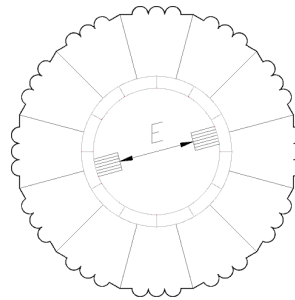
$$M = k \cdot \Phi \cdot I \quad (\text{Nm}) \quad \uparrow I \text{ ili } \uparrow \Phi \Rightarrow \uparrow M$$

struja armature proporcionalno I_U

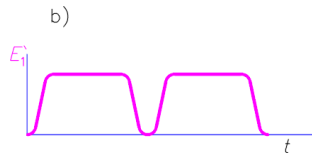
Inducirani napon i komutirani napon armature



inducirani napon jednog zavoja

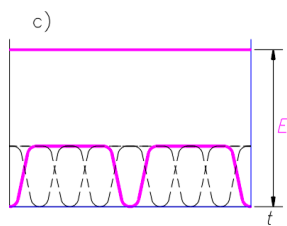


spoj svih namota petljasto izvedene armature

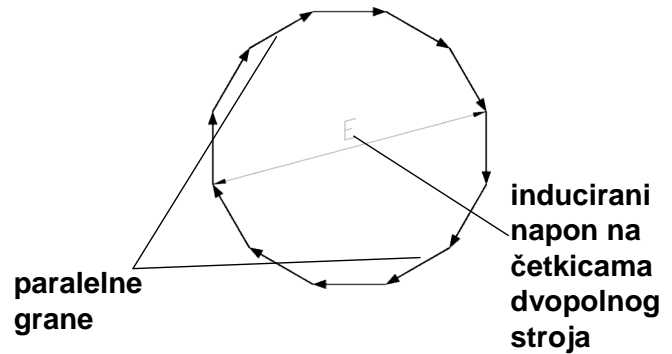


komutacijom ispravljeni napon jednog zavoja

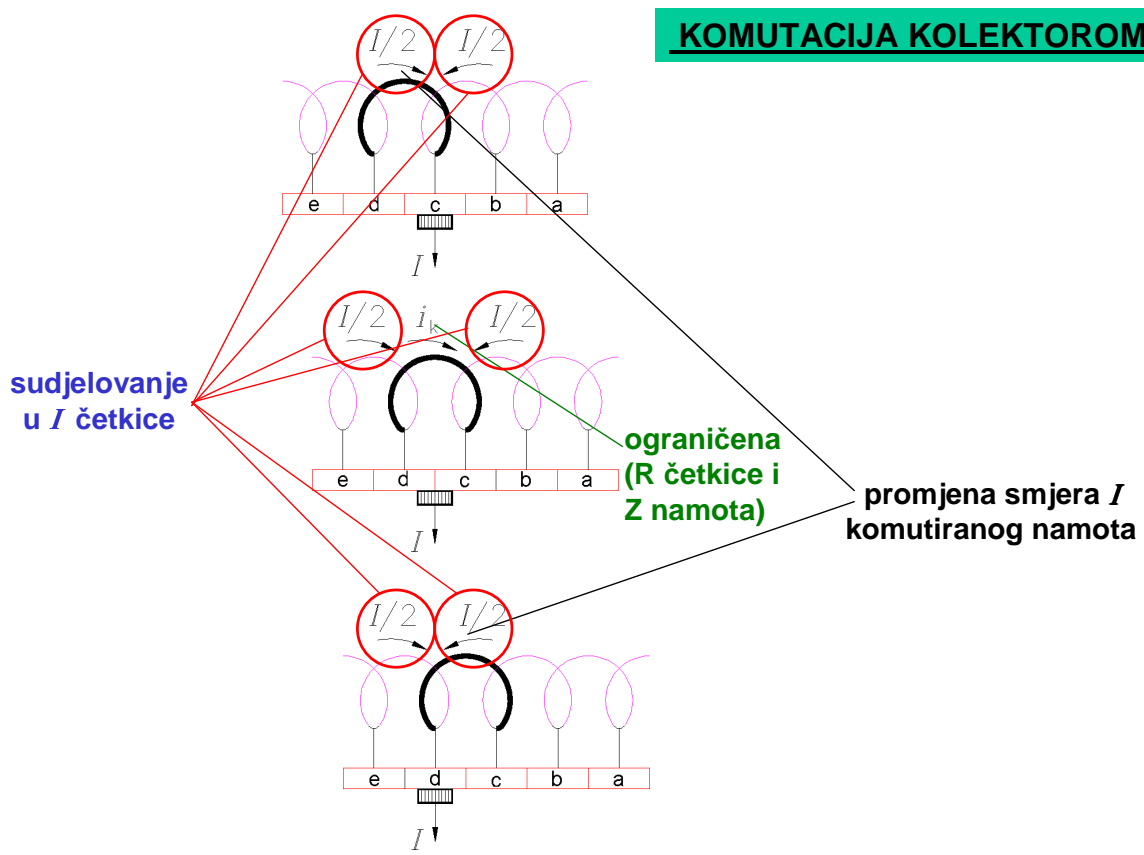
induciraju se višefazni naponi kazala svih namota petljasto izvedene armature



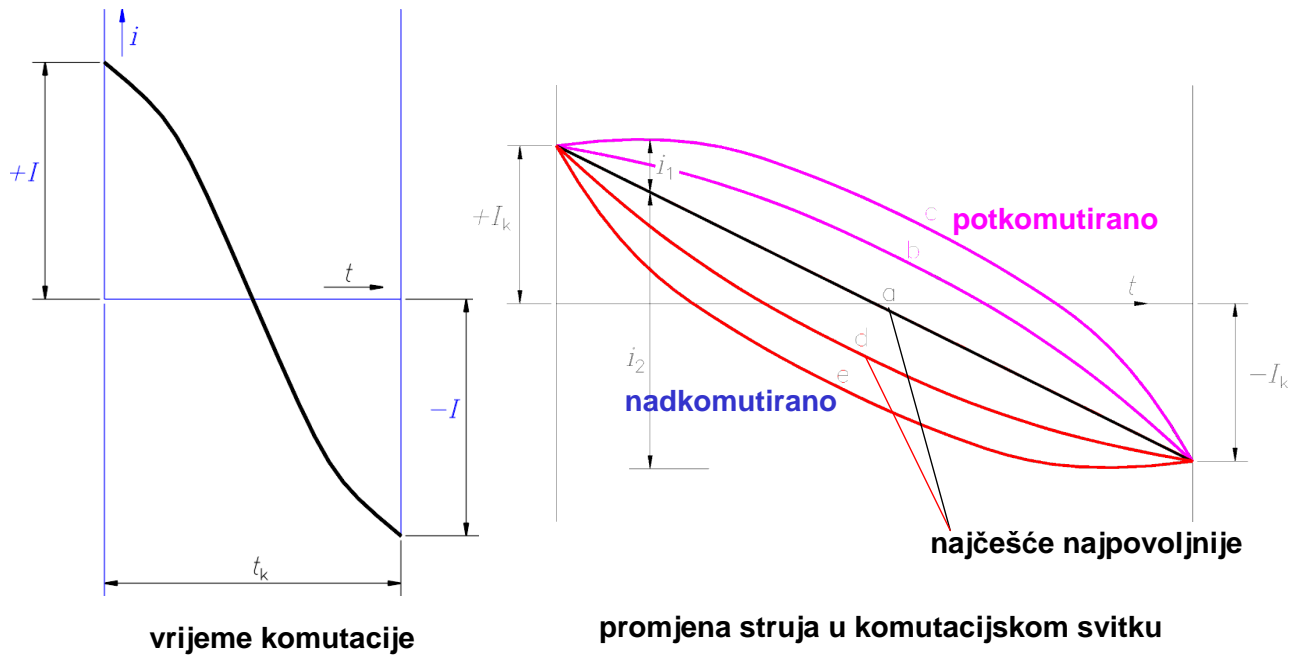
ukupni komutacijom ispravljeni napon svih zavoja



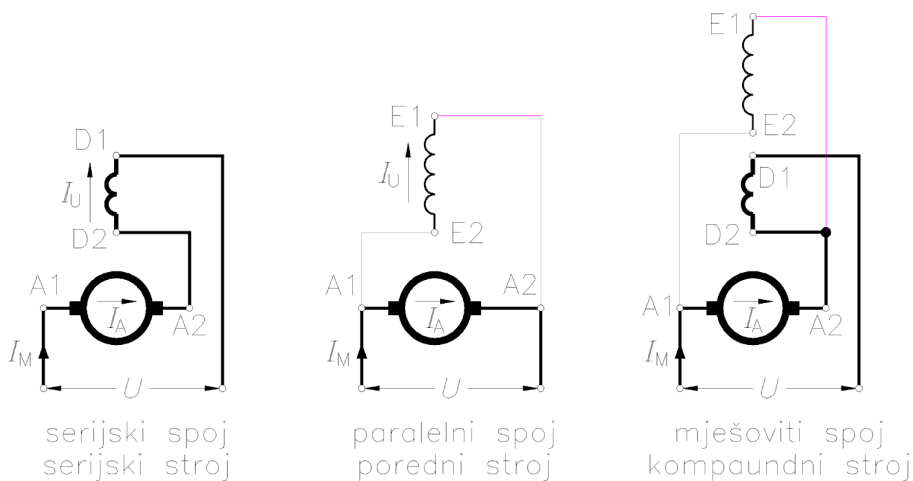
KOMUTACIJA KOLEKTOROM



L namota \Rightarrow protivljenje promjeni smjera struje \Rightarrow induciranje prenapona \Rightarrow iskrenje



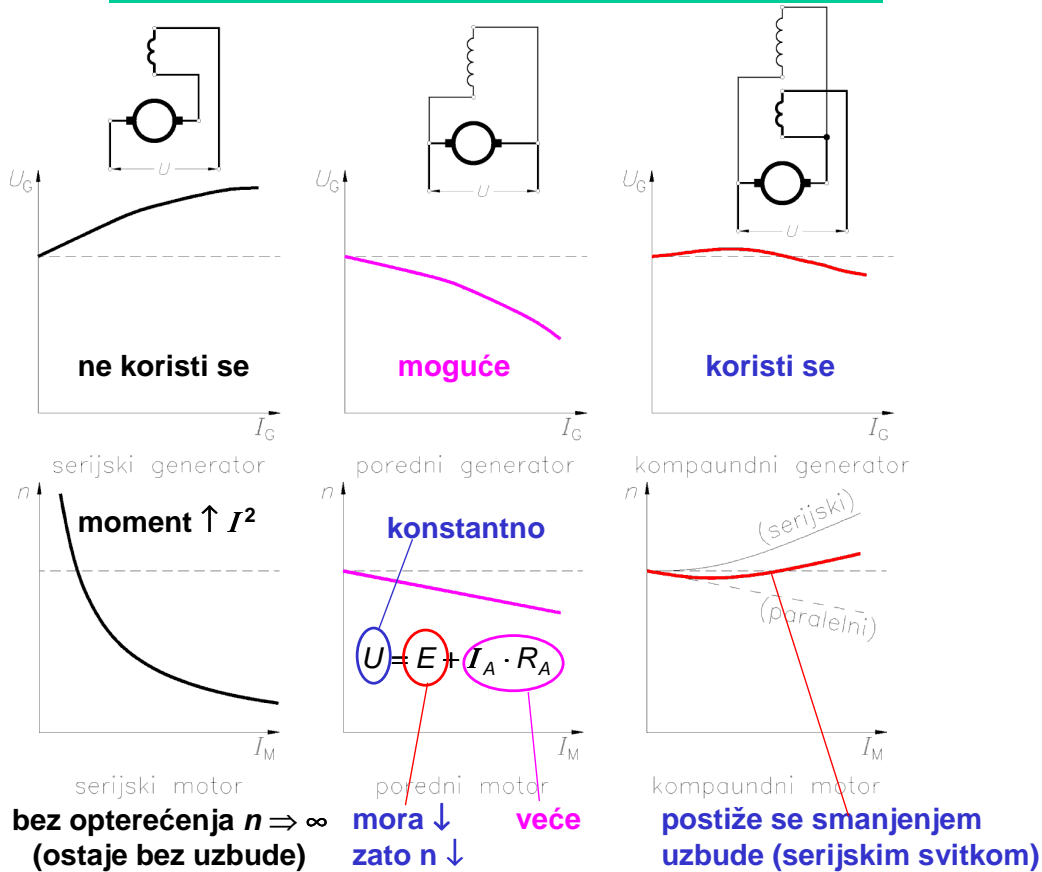
SPOJEVI ISTOSMJERNIH STROJEVA



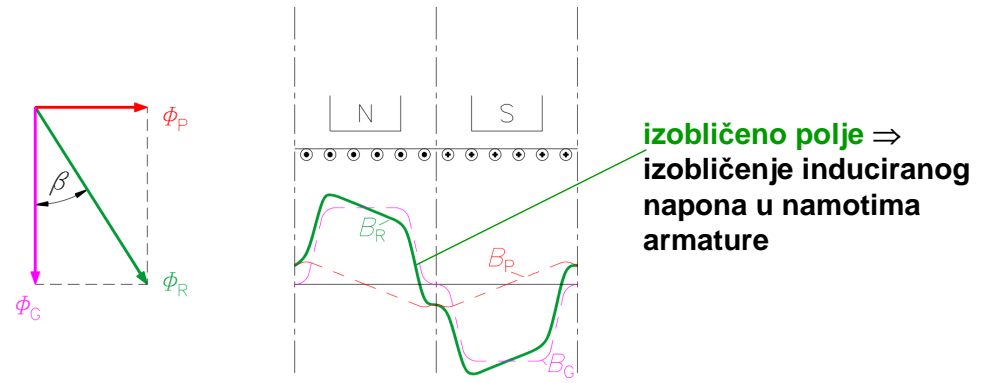
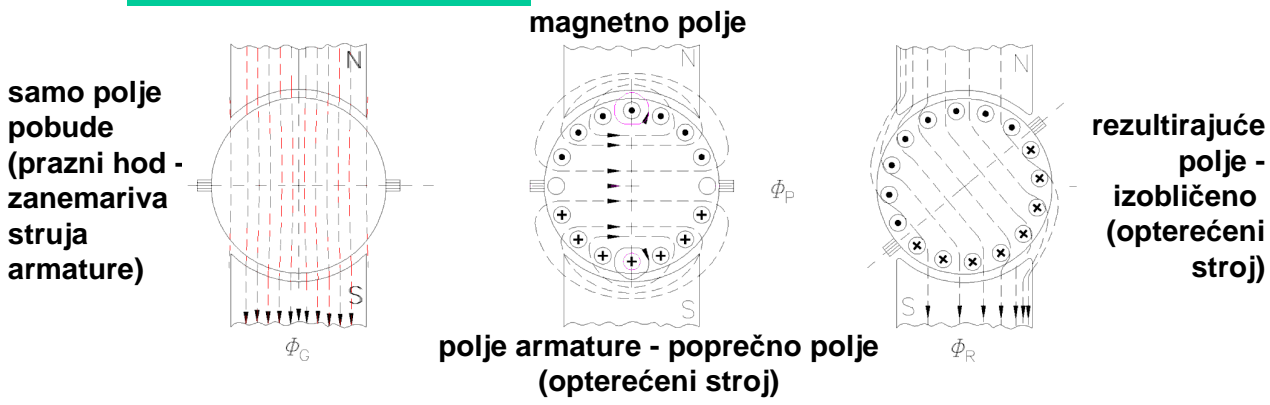
označivanje priključaka strojeva

- serijski stroj četkice - A1 A2 (A B) uzbudni svitak - D1 D2 (E F)
- poredni stroj četkice - A1 A2 (A B) uzbudni svitak - E1 E2 (C D)
- kompaundni stroj četkice - A1 A2 (A B) uzbudni svitci - D1 D2 (E F) i E1 E2 (C D)
- nezavisna uzbuda četkice - A1 A2 (A B) uzbudni svitci - F1 F2

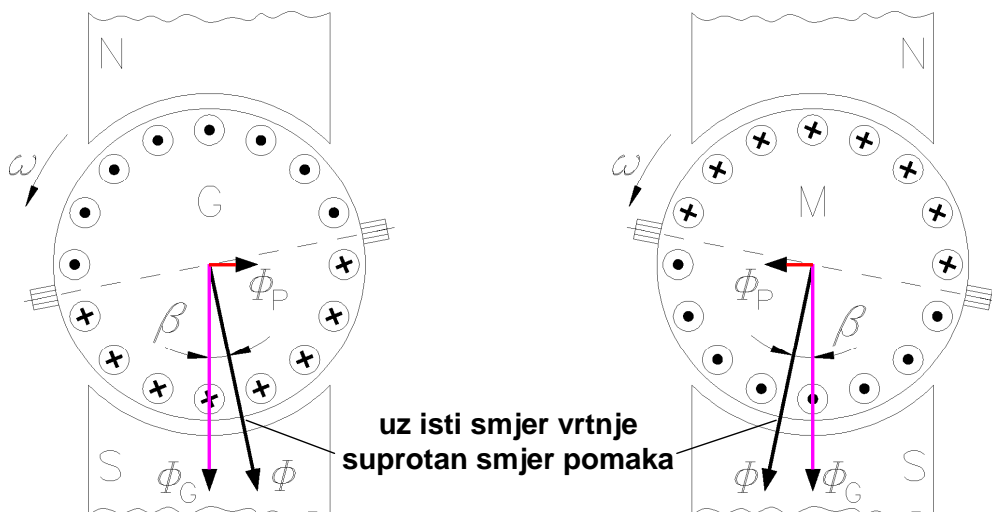
KARAKTERISTIKE ISTOSMJERNIH STROJEVA



REAKCIJA ARMATURE



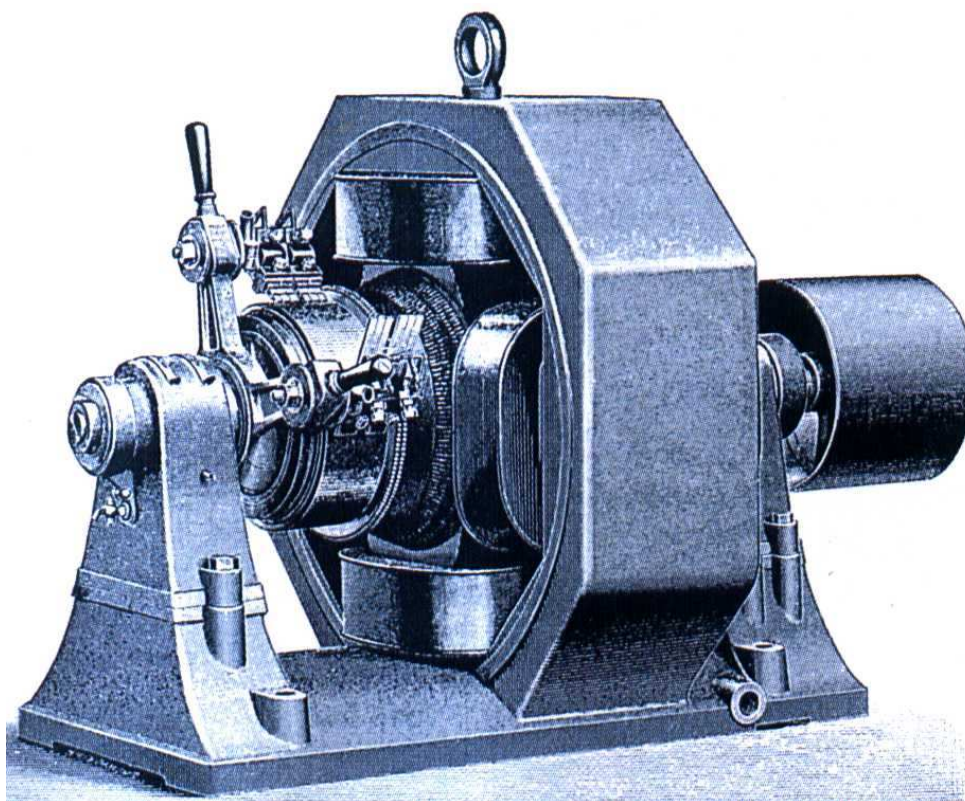
Neutralna zona



$\uparrow I_G \Rightarrow \uparrow \beta \Rightarrow \uparrow$ pomak neutralne zone

$\uparrow I_M \Rightarrow \uparrow \beta \Rightarrow \uparrow$ pomak neutralne zone

četkica izvan neutralne zone \Rightarrow jaće iskrenje, brže trošenje



Kompensacija reakcije armature

