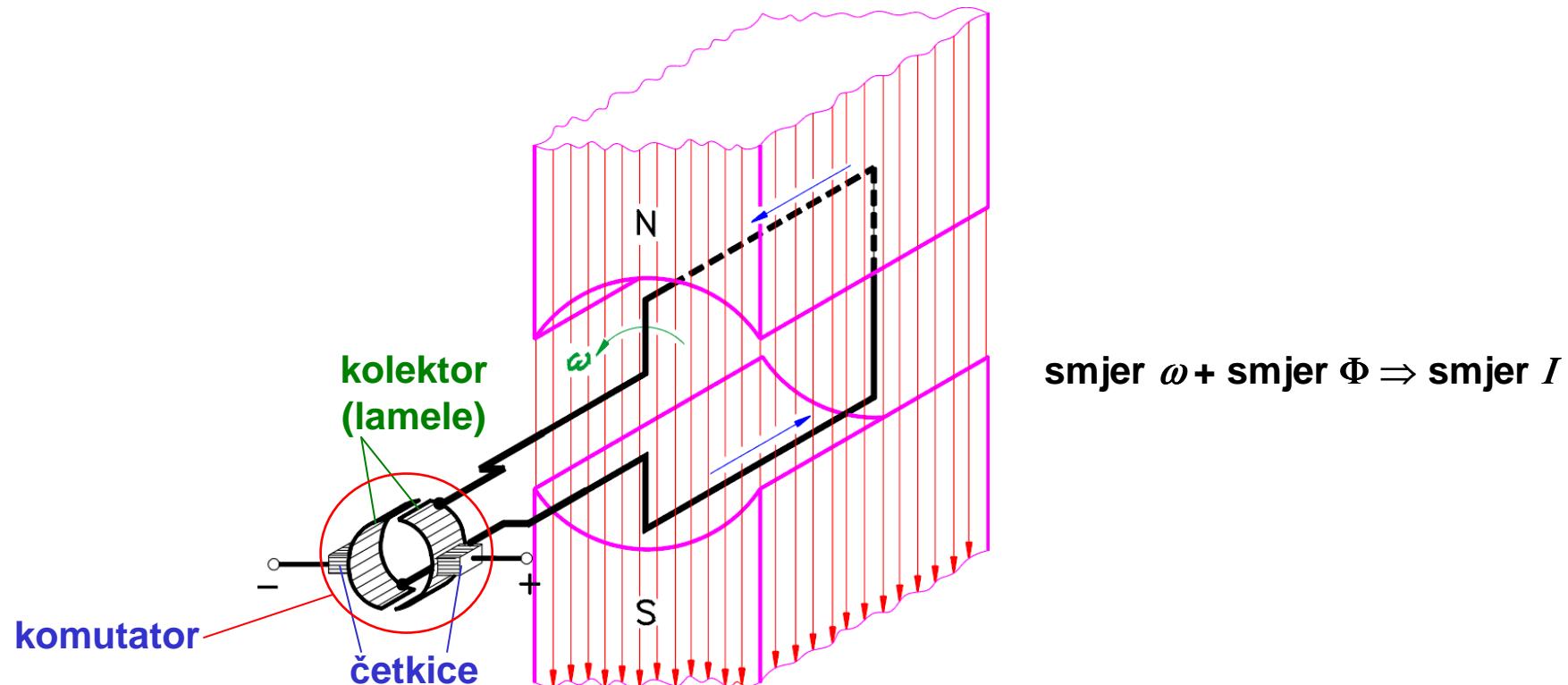


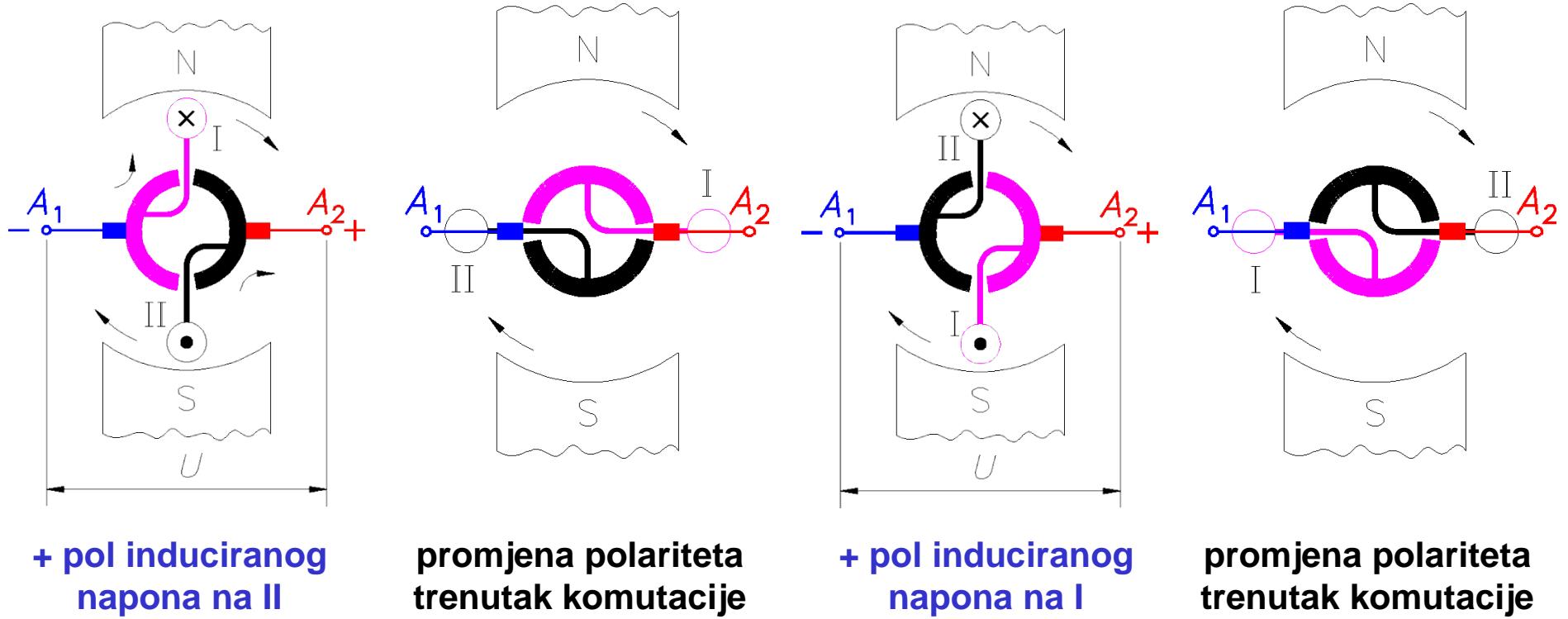
## ISTOSMJERNI STROJEVI

jedini strojevi do Tesle a onda marginalizirani  
bili nezamjenjivi za promjenjivu brzinu vrtnje i promjenjivi moment  
glavna merna komutacija (održavanje i smetnje)  
dan - nezavisna uzbuda s poluvodičkim komponentama i komutacijom na statoru  
uzbudni namot na statoru - armaturni namot na rotoru

### Induciranje istosmjernog napona

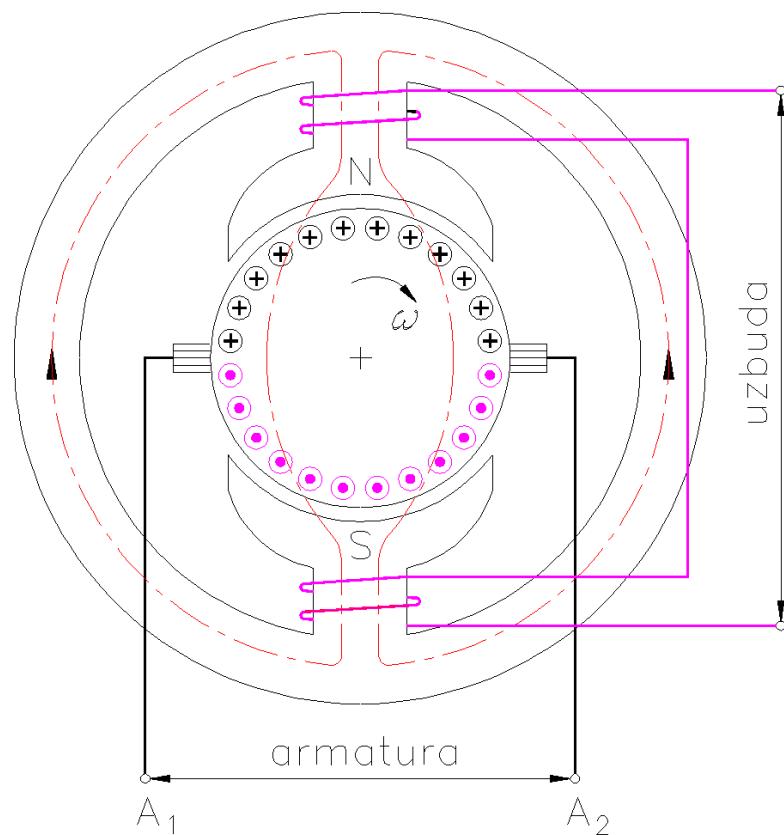


## Komutiranje induciranih napona (struje) u istosmjerni

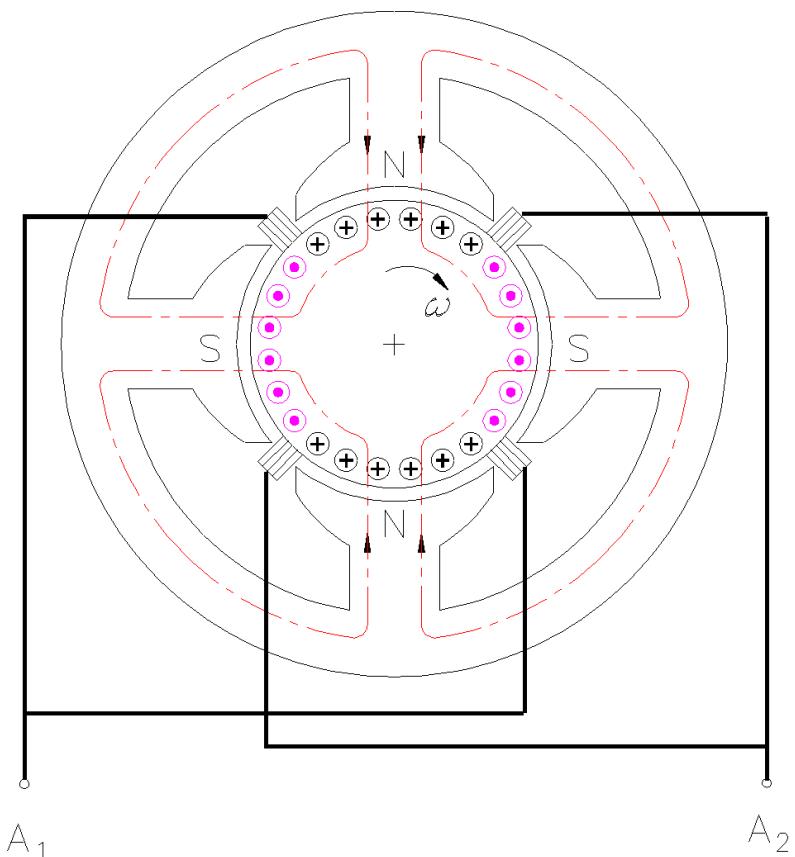


četkice u neutralnoj zoni (okomito na glavno magnetno polje)  
komutacija pri trenutna vrijednosti induciranih napona 0

**dvopolni stroj**



**četveropolni stroj**



jedno

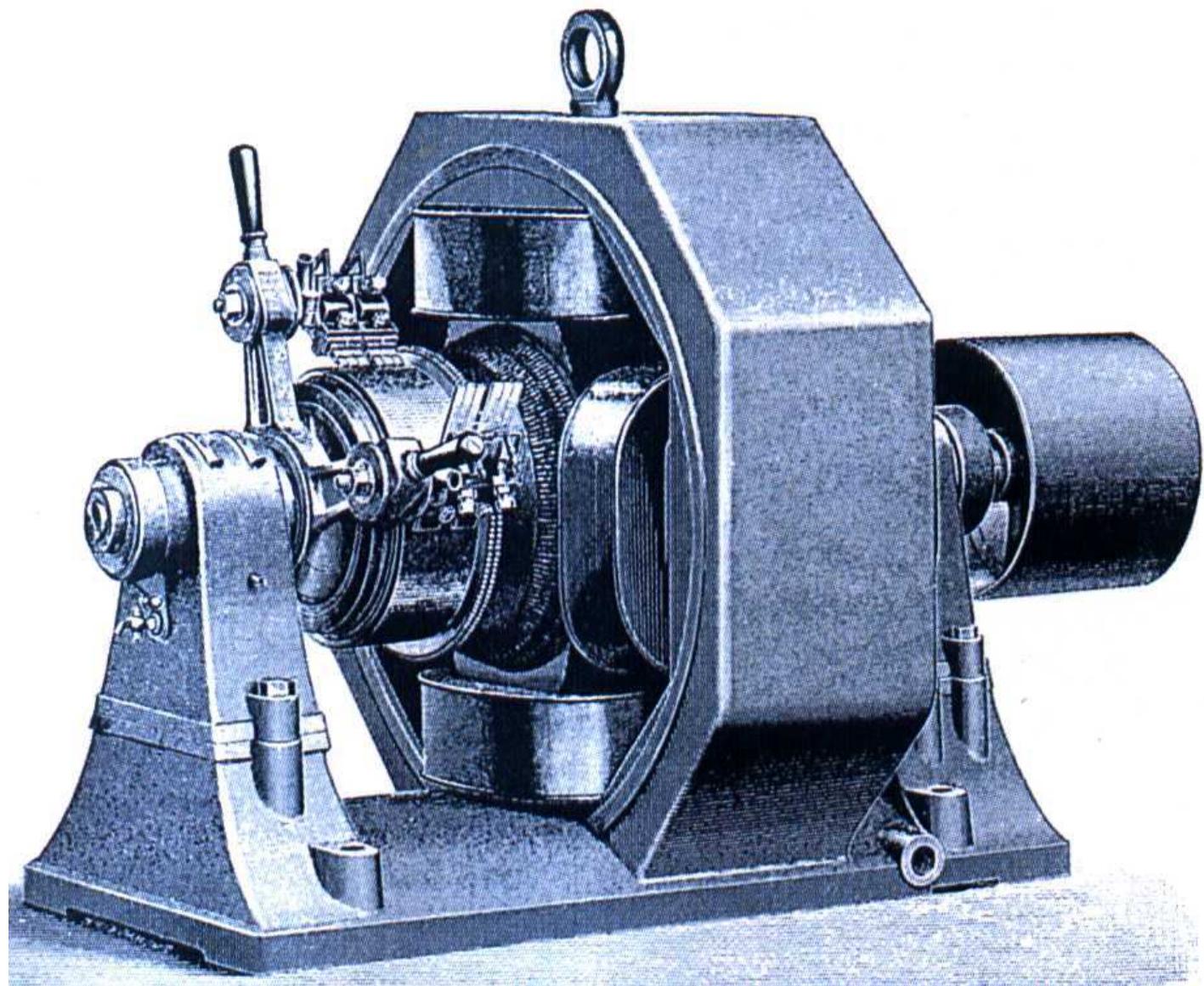
homogenih magnetnih polja

dva

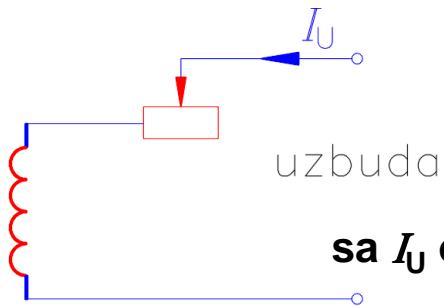
cijeli ciklus = jedan okretaj

cijeli ciklus = pola okretaja

uz jednak  $n$  namota rotora za jednake vrijednosti napona  $\Rightarrow$  više polova = manja brzina vrtnje

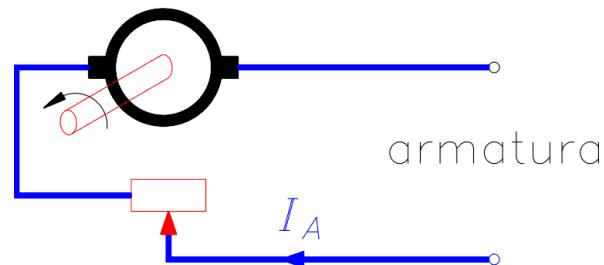


strujni krugovi  
istosmjernih strojeva

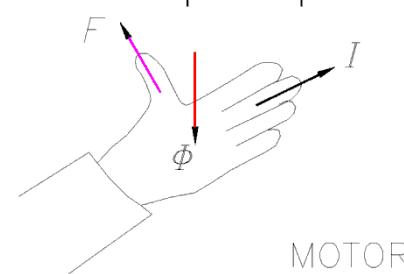
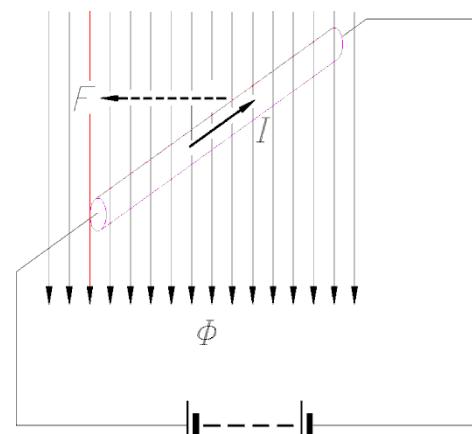
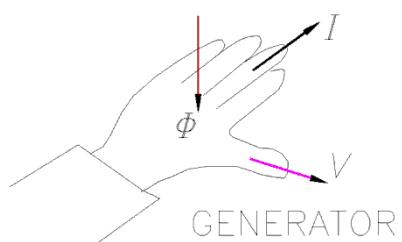
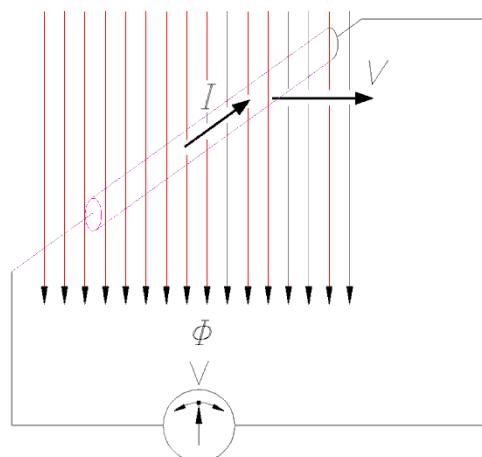


nezavisni (regulirani pogoni)  
zavisni (stalni odnos  $I_U$  i  $I_A$ )

sa  $I_U$  određivanje  $B \Rightarrow$  inducirani  $U$  armature



sa  $I_A$  biranje funkcije stroja

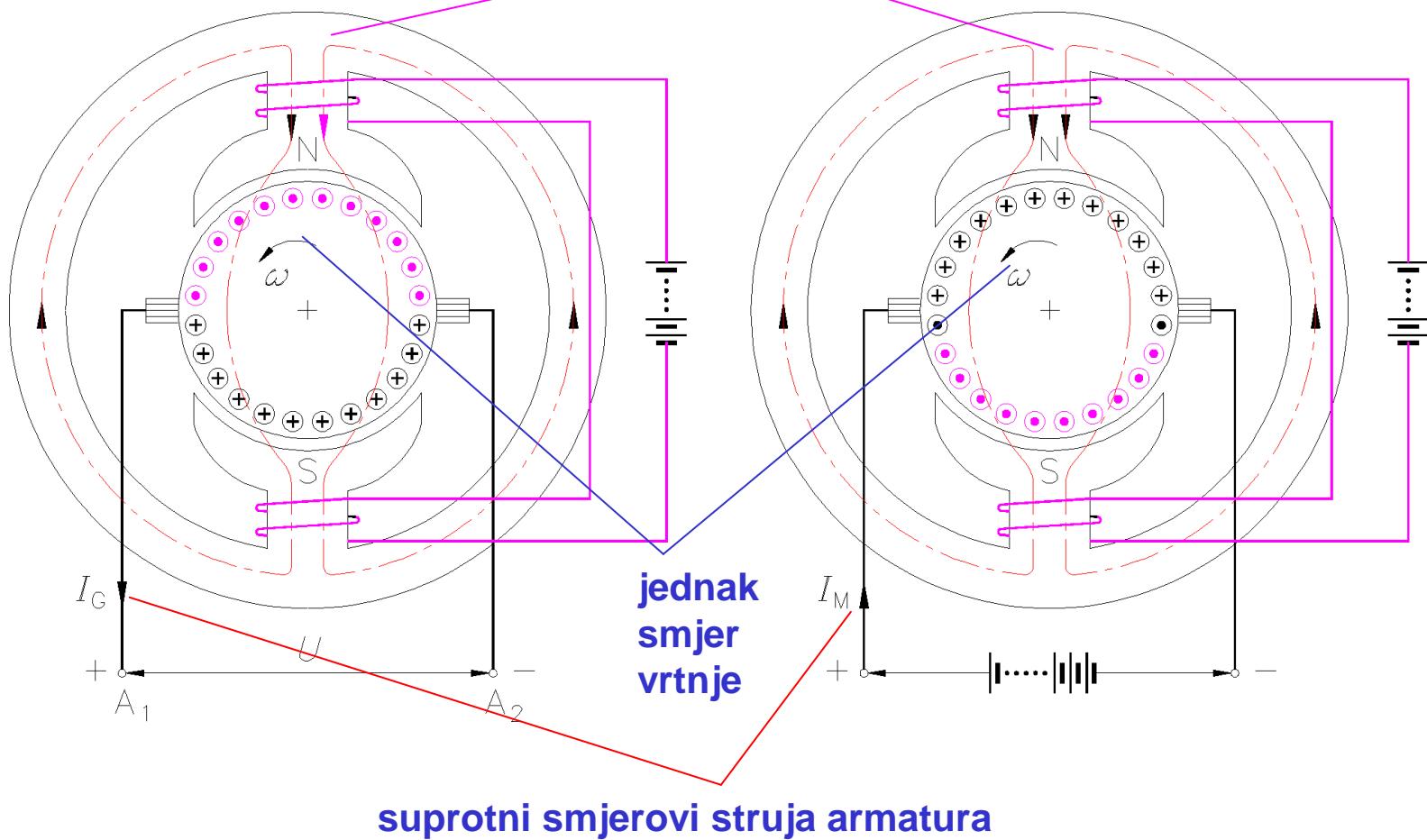


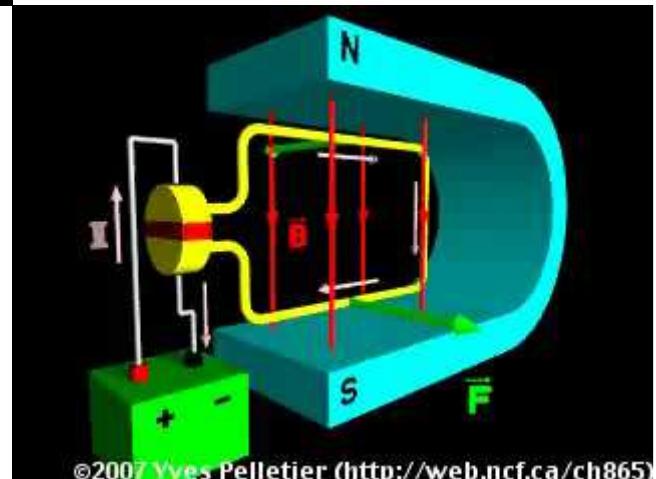
za isti smjer struje i  
magnetnog polja  
suprotni smjerovi  
gibanja vodiča kod  
generatora imotora

istosmjerni generator

istosmjerni motor

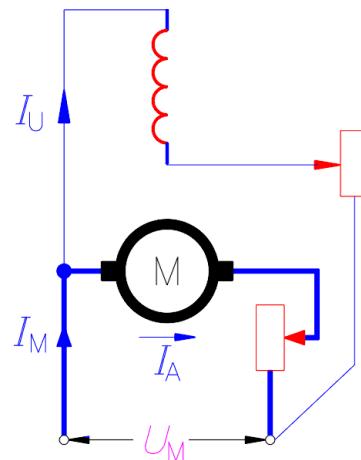
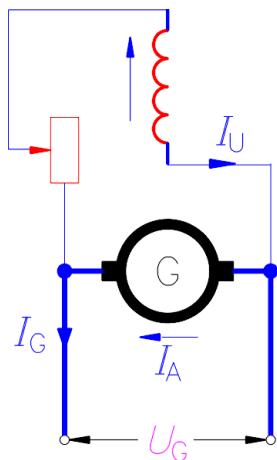
jednak smjer struje uzbude (magnetskog polja uzbude)





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## zavisni (paralelni) istosmjerni strojevi



## pad napona na namotu rotora (armature)

uz poznati  $E$  za generator  $U = E - I_A \cdot R_A$   
 uz poznati  $E$  za motor  $U = E + I_A \cdot R_A$

sila je  $F = B \cdot I \cdot l$  (N) a moment motora  $M = 2 \cdot F \cdot r = B \cdot I \cdot l \cdot 2r = B \cdot S \cdot I = \Phi \cdot I$  (Nm)

## srednja vrijednost induciranih naponova rotora

$$u_{is} = N \frac{\Delta \Phi}{\Delta t}$$

uz  $\Delta \Phi = 2 \cdot \Phi$  i  $\Delta t = \frac{60}{n \cdot p}$   
 zavoji rotora  $+ \Phi$  do  $- \Phi$  vrtanja polova

## a ukupni inducirani napon

$$E = 2 \cdot \Phi \cdot \frac{N \cdot n \cdot p}{z} \cdot \frac{60}{30 \cdot z} \quad (\text{v})$$

paralelnih grana namota

ili  $E = B \cdot I \cdot v \quad (\text{v})$

$$\Delta U_A = I_A \cdot R_A$$

$$E = k \cdot \Phi \cdot n \quad \uparrow \Phi \Rightarrow \uparrow E (U)$$

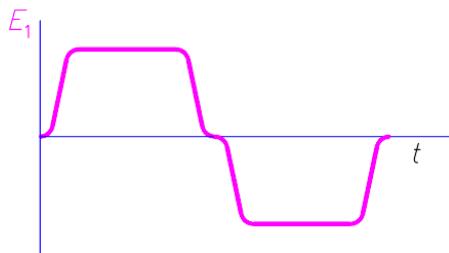
$$n = \frac{E}{k \cdot \Phi} \approx \frac{U}{k \cdot \Phi} \quad \uparrow \Phi \Rightarrow \downarrow n \quad i \Leftrightarrow$$

$$M = k \cdot \Phi \cdot I \quad (\text{Nm})$$

$\uparrow I$  ili  $\uparrow \Phi \Rightarrow \uparrow M$   
 struja armature proporcionalno  $I_U$

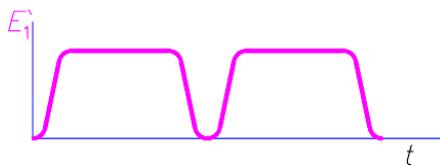
## Inducirani napon i komutirani napon armature

a)



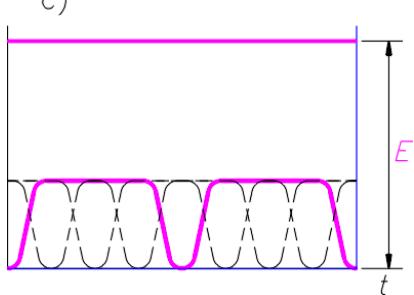
inducirani  
napon  
jednog  
zavoja

b)

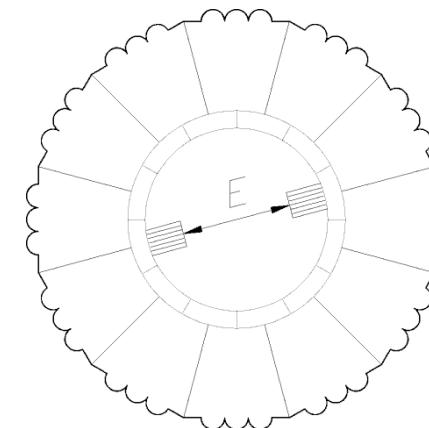


komutacijom  
ispravljeni  
napon  
jednog  
zavoja

c)



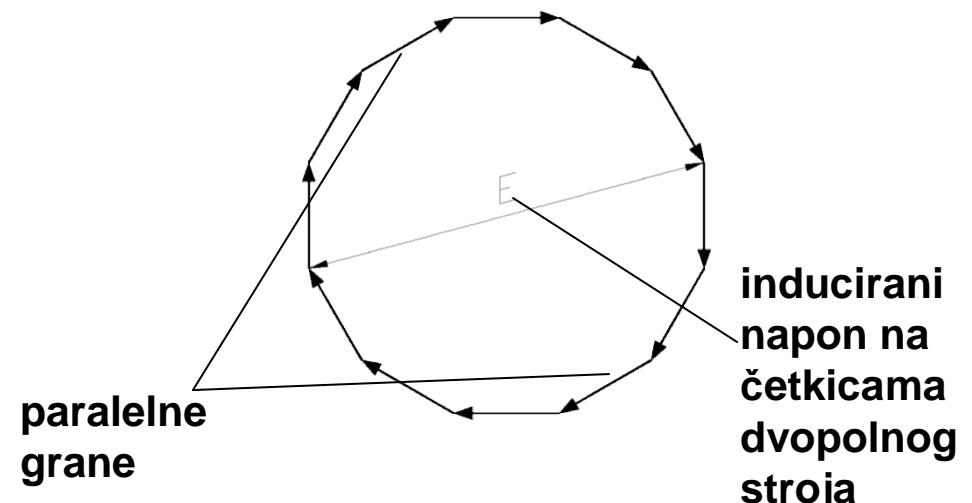
ukupni  
komutacijom  
ispravljeni  
napon svih  
zavoja



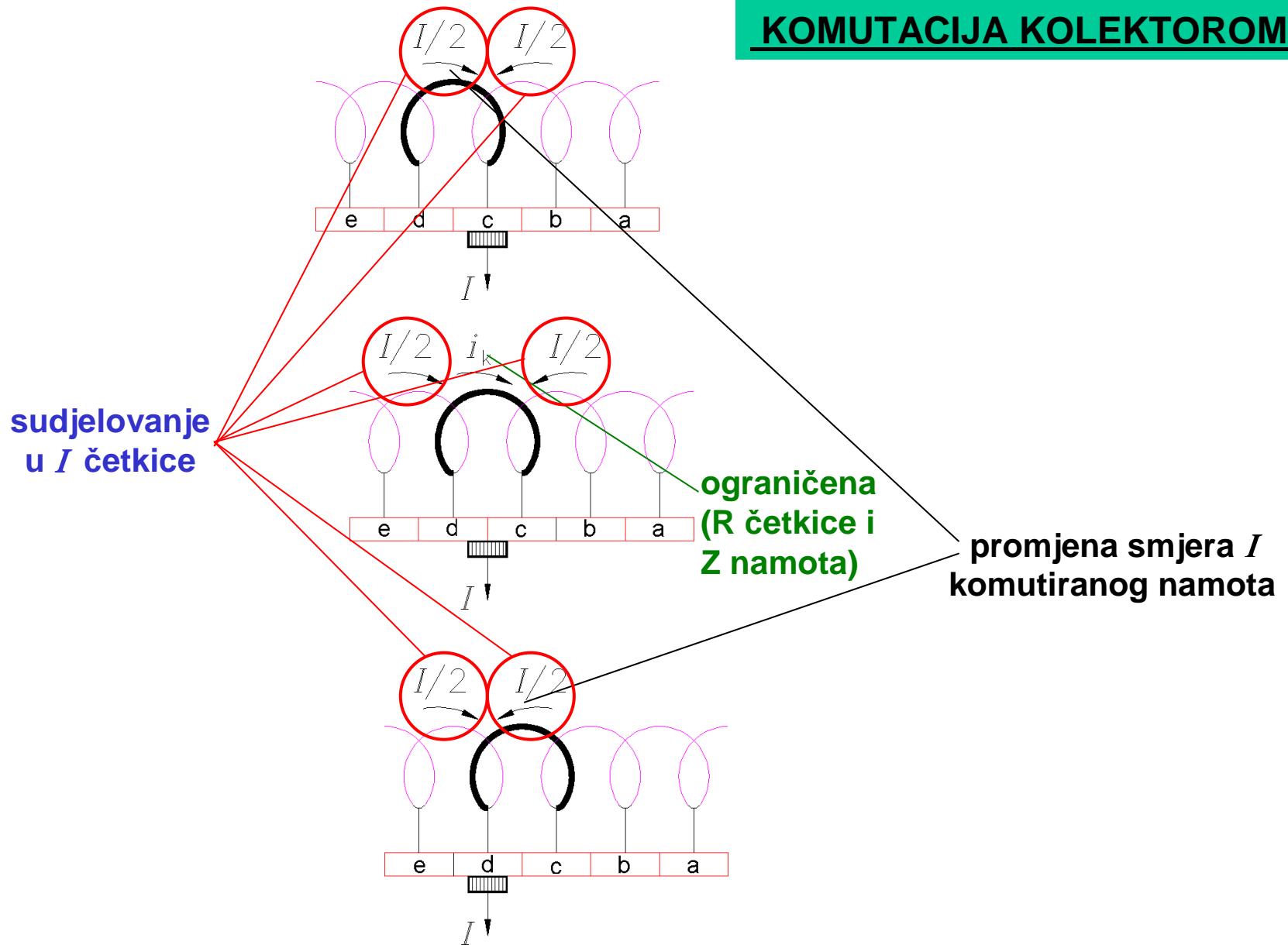
spoј svih  
namota  
petljasto  
izvedene  
armature

induciraju se višefazni naponi

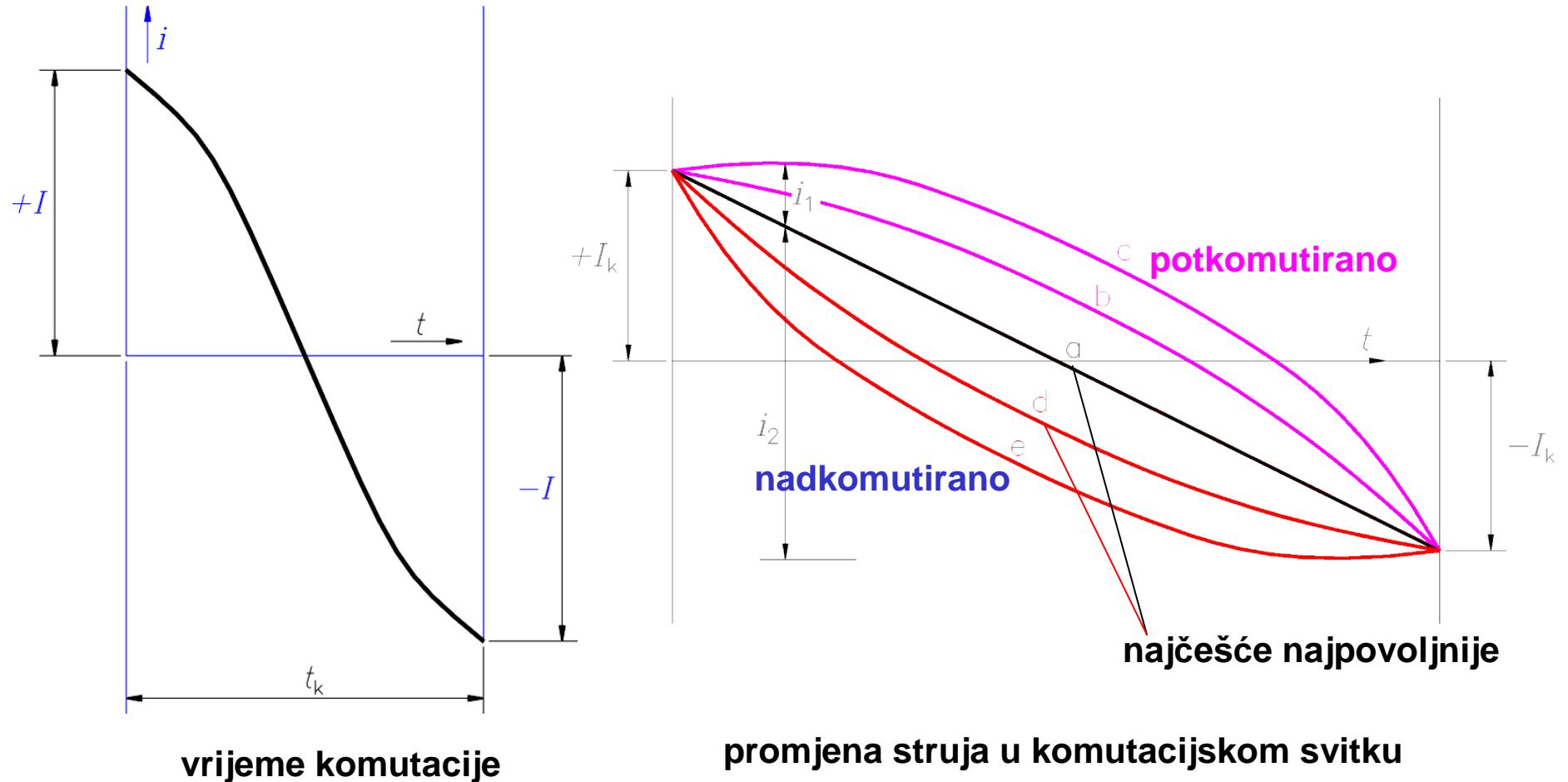
kazala svih namota  
petljasto izvedene armature



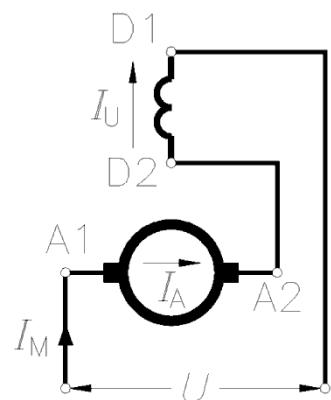
## KOMUTACIJA KOLEKTOROM



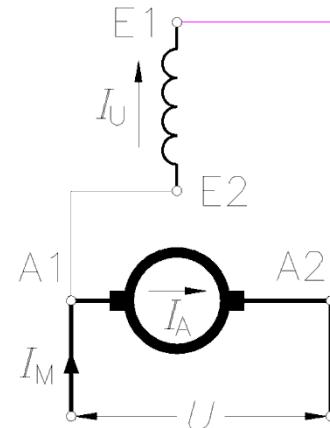
$L$  namota  $\Rightarrow$  protivnjene promjeni smjera struje  $\Rightarrow$  inducirane prenapona  $\Rightarrow$  iskrenje



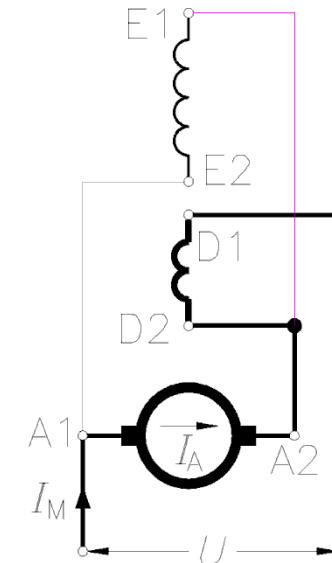
## SPOJEVI ISTOSMJERNIH STROJEVA



serijski spoj  
serijski stroj



paralelni spoj  
poredni stroj



mješoviti spoj  
kompaundni stroj

### označivanje priključaka strojeva

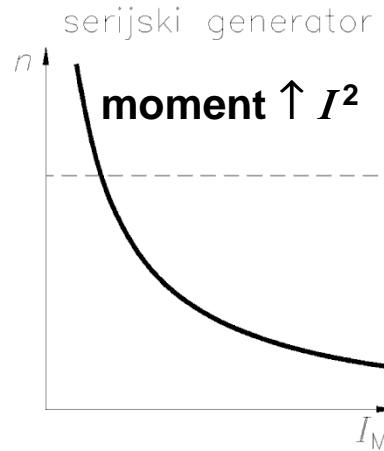
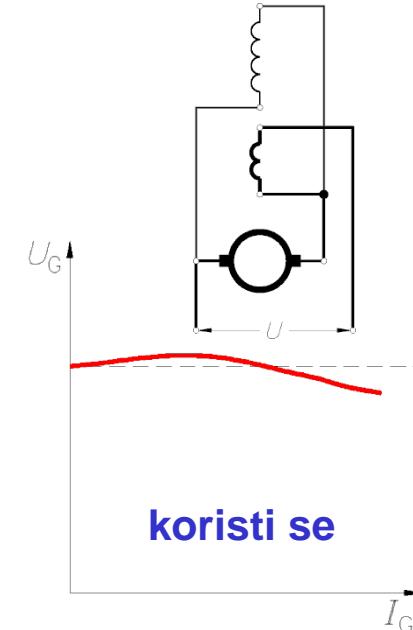
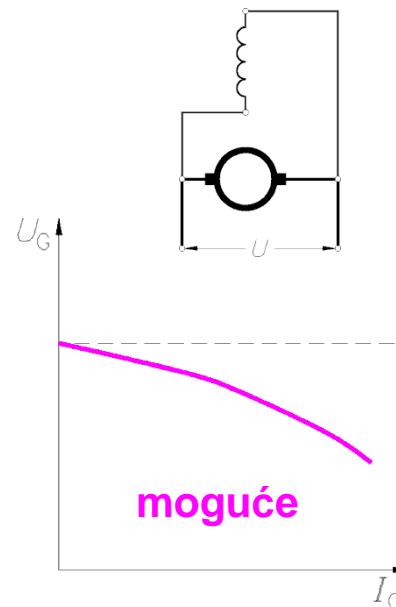
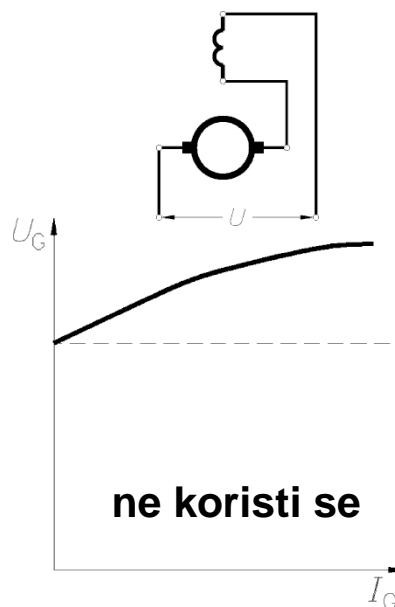
**serijski stroj četkice - A1 A2 (A B) uzbudni svitak - D1 D2 (E F)**

**poredni stroj četkice - A1 A2 (A B) uzbudni svitak - E1 E2 (C D)**

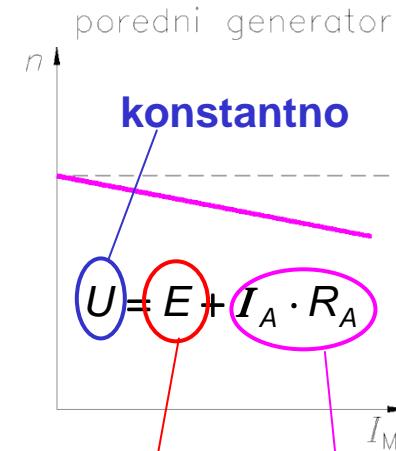
**kompaundni stroj četkice - A1 A2 (A B) uzbudni svitci - D1 D2 (E F) i E1 E2 (C D)**

**nezavisna uzbuda četkice - A1 A2 (A B) uzbudni svitci - F1 F2**

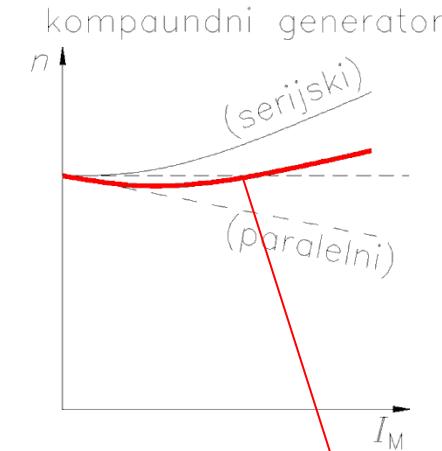
## KARAKTERISTIKE ISTOSMJERNIH STROJEVA



serijski motor  
bez opterećenja  $n \Rightarrow \infty$   
(ostaje bez uzbude)



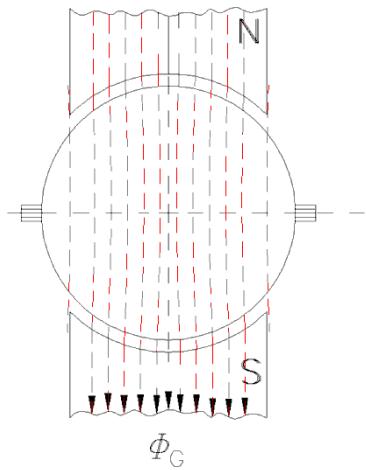
poredni motor  
**mora  $\downarrow$**   
**veće**  
 **$n \downarrow$**



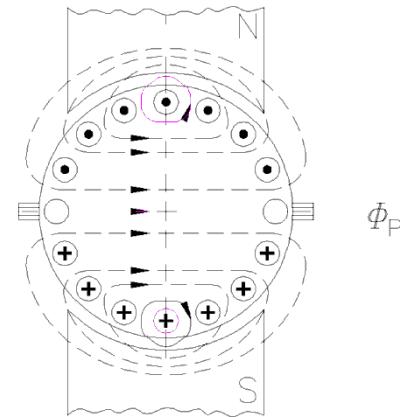
kompaundni motor  
**postiže se smanjenjem**  
**uzbude (serijskim svitkom)**

## REAKCIJA ARMATURE

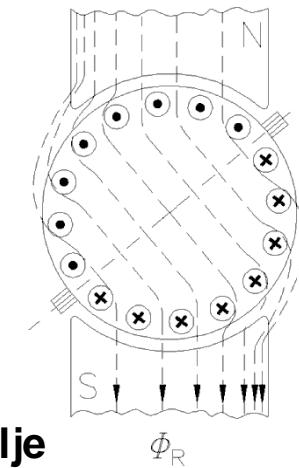
samo polje  
pobude  
(prazni hod -  
zanemariva  
struja  
armature)



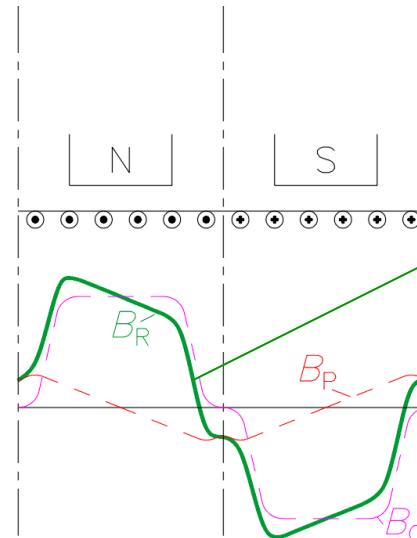
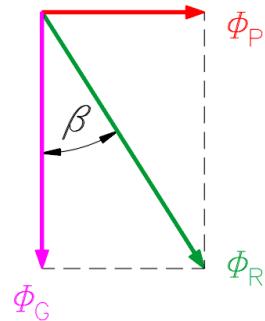
magnetno polje



polje armature - poprečno polje  
(opterećeni stroj)

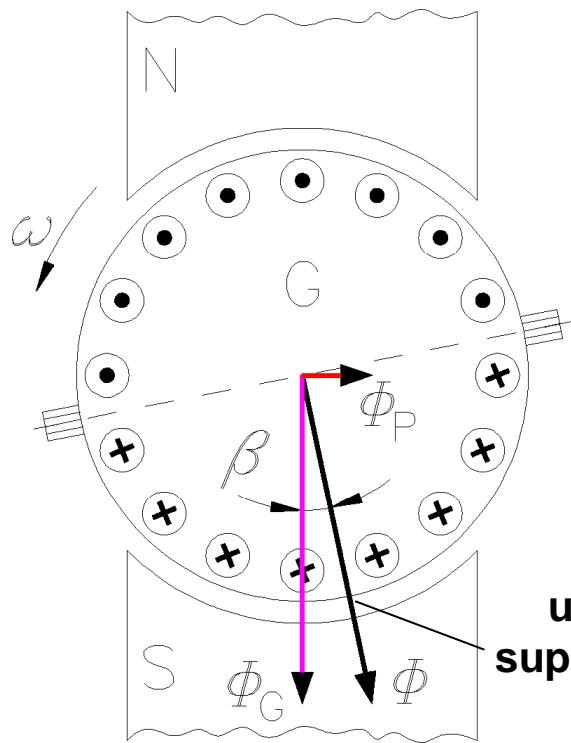


rezultirajuće  
polje -  
izobličeno  
(opterećeni  
stroj)

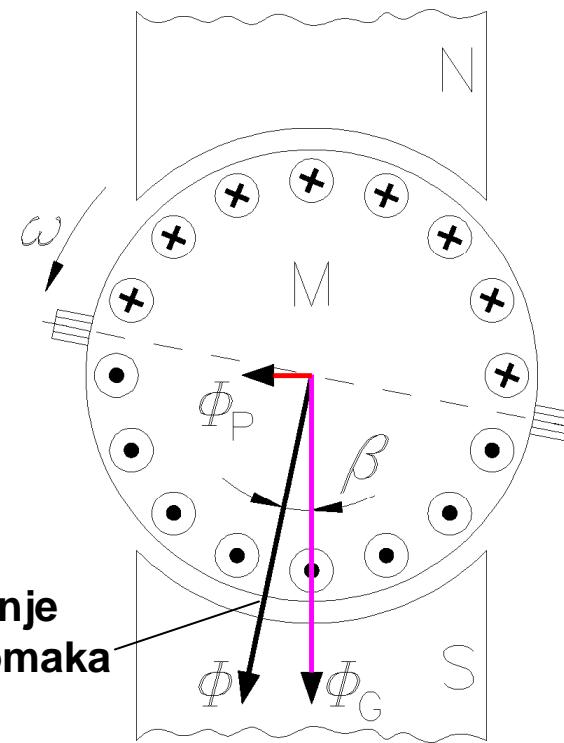


izobličeno polje  $\Rightarrow$   
izobličenje induciranih  
napona u namotima  
armature

## Neutralna zona



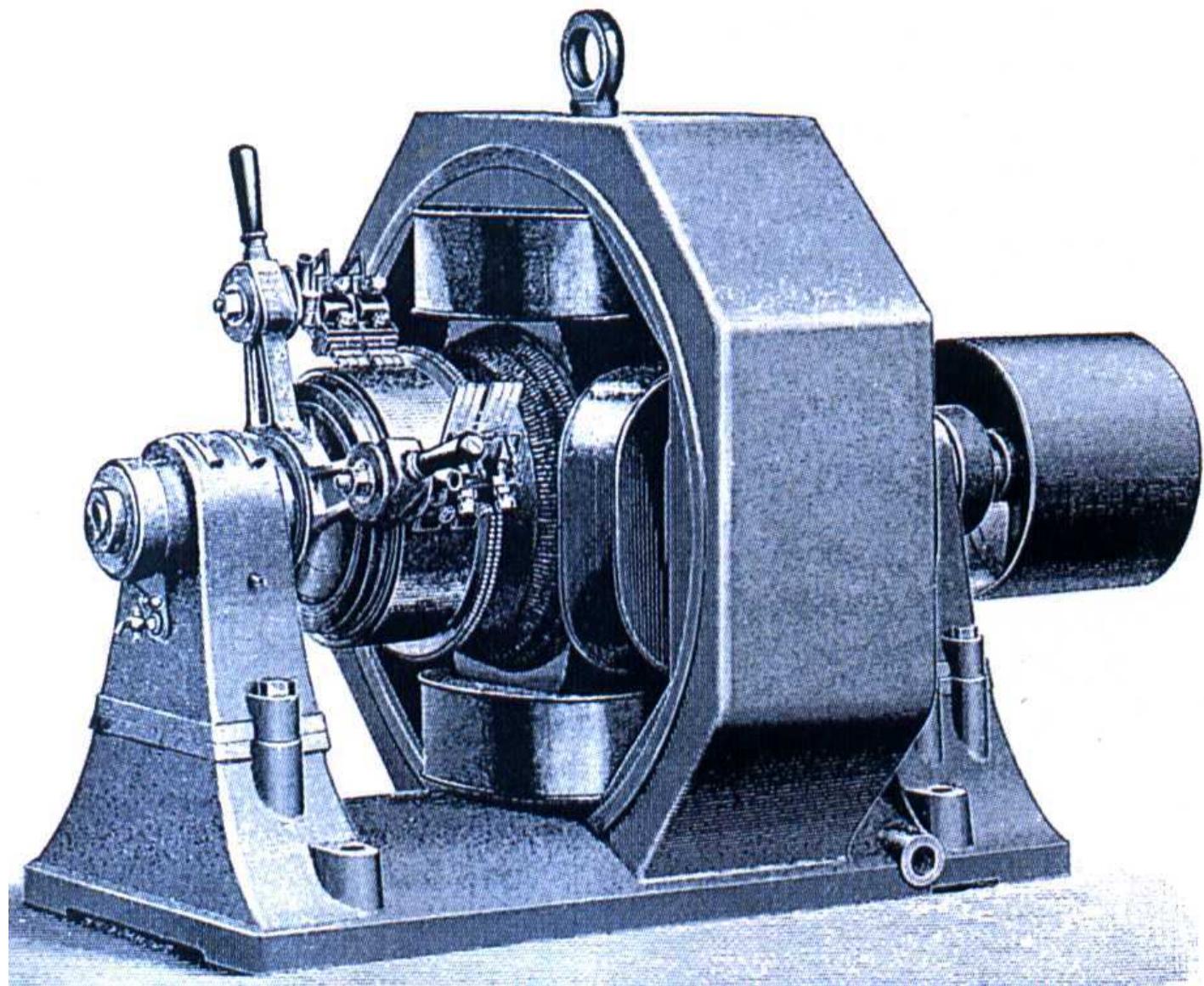
**uz isti smjer vrtnje  
suprotan smjer pomaka**



$\uparrow I_G \Rightarrow \uparrow \beta \Rightarrow \uparrow \text{pomak neutralne zone}$

$\uparrow I_M \Rightarrow \uparrow \beta \Rightarrow \uparrow \text{pomak neutralne zone}$

**četkica izvan neutralne zone  $\Rightarrow$  jaće iskrenje, brže trošenje**



## Kompenzacija reakcije armature

